



Wireless Sensor Networks Technology and Simulation Software Overview

AJAY SONKESRIYA

Lecturer

Electronics and Communication Engineering
Kalaniketan polytechnic College Jabalpur MP

Abstract: A new generation of massive-scale sensor networks has been enabled by advancements in wireless networking, microfabrication, and integration of sensors and actuators created using micro-electromechanical system (MEMS) technology and embedded microprocessors. Sensor networks have the potential to connect end users directly to sensor readings and give information that is accurately localised in time and/or location, based on the user's requirements. Simulators that replicate the behaviour of a sensor network on a per-node basis are known as node-level design simulators. Designers can quickly assess performance in terms of timing, power, bandwidth, and scalability using simulation rather than implementing them on real hardware and dealing with physical phenomena. The current communication provides an overview of wireless sensor networks (WSNs), as well as information on WSN components, operating systems (TinyOS, RIOT, Nano-RK, MANTIS, and others), and WSN simulation software (NS2, OMNET++, J-Sim, JiST, GloMoSim, SSFNet, and others). The goal is to give learners/researchers a better grasp of current research concerns in this field and to define the use of specific tools to accomplish design objectives that will help them construct WSN applications.

Keywords: Sensor nodes, Architecture, Operating system, Simulation software, Wireless technology.

I. INTRODUCTION

In the nineteenth century, the phrase "wireless communication" was coined. Marconi made the first radio transmission from the Isle of Wright to Tugboat, 18 miles away, in 1895. Information can be conveyed by electromagnetic waves via the air without the use of wires or electronic conductors in this technology. Wireless communication technology is used in sensing, monitoring, smart phones, computers, Bluetooth technology, and networking at the moment.

The existing Internet is extended deep into the physical environment by sensor networks. The resulting new network is more vast and dynamic than today's TCP/IP network, and it's generating totally new sorts of traffic that aren't found on the Internet today. To efficiently support user-level tasks, information gathered by and delivered on a sensor network specifies conditions of physical environments, such as temperature, humidity, or vibration, and requires powerful query interfaces and search engines.

Compared to typical centralised techniques, networked sensing has numerous advantages. By reducing average distances between sensor and signal source, or destination,

dense networks of distributed communicating sensors can enhance signal-to-noise ratio (SNR) [1]. The multi-hop design of the network allows for increased energy efficiency in communications. Furthermore, in-network processing can combine additional relevant data from other sensors during this multi-hop transmission. Improved robustness and scalability are the most significant benefits of networked sensing. Individual sensor node or link failures are less likely in a decentralised sensing system.

Decentralized algorithms are also significantly more scalable in practise, and for some applications, they may be the only method to achieve the massive scales required [2].

WIRELESS SENSOR NETWORK ARCHITECTURE

Wireless sensor network (WSN) or wireless sensor & actuator network (WSAN) are spatially distributed sensors to monitor physical or environmental conditions such as temperature, humidity, fire etc. and to cooperatively pass their data through the network to the main location. WSN consist of three main components nodes, gateways and the software. The sensors measure the parameter of interest & transmit their data wirelessly through the gateway to the host system where the software collects the data, processes it so that it can be analysed [2,3].

A. Sensor node or Mote

The main components of the WSN sensor node is radiomodem, controller, sensor and power supply. The block diagram of sensor node is shown in Fig.1.

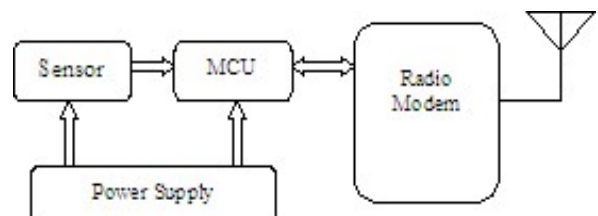


Fig.1. Block diagram of sensor node

1. Radiomodem:

They often make use of ISM band which gives free radio spectrum allocation and global availability. WSN uses three licence free communication frequency bands 868MHz, 915MHz and 2.4GHz.



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2. Controller:

The controller performs tasks, processes data and controls the functionality of other components in the sensor node. The analogue signals produced from the sensor are converted into digital signals by the analogue to digital converter (ADC) and fed to the processing unit.

3. Sensors:

They are the hardware devices that produce a measurable response to a change in physical condition. They have small size and are typically large in numbers so as to measure maximum parameters.

4. Power supply:

The WSN is designed without the need of human intervention as they are placed in hard to reach location. The battery forms the heart of the sensor system as it decides the lifespan of the system. Hence battery plays an important role in ensuring that there is adequate energy available to power the system.

B. Gateway

The Gateway acts as a bridge between the WSN and the other network. The Gateway collects the information received from the nodes in a database and makes this information available usually via a wireless network [3]. Sensor networks may interconnect with an IP core network via a number of gateways. A gateway routes user queries or commands to appropriate nodes in a sensor network. It also routes sensor data, at times aggregated and summarized, to users who have requested it or are expected to utilize the information.

C. Software

A typical Operating System (OS) abstracts the hardware platform by providing a set of services for applications, including file management, memory allocation, task scheduling, peripheral device drivers, and networking. For embedded systems, due to their highly specialized applications and limited resources, their operating systems make different trade-offs when providing these services. For example, if there is no file management requirement, then a file system is obviously not needed. If there is no dynamic memory allocation, then memory management can be simplified. If prioritization among tasks is critical, then a more elaborate priority scheduling mechanism may be added. TinyOS, MATE, a Virtual Machine for the Berkeley nodes and TinyGAL are examples of node-level programming tools. Different available OS are [4,5]

TinyOS: TinyOS has no file system, supports only static memory allocation, implements a simple task model, and provides minimal device and networking abstractions. Furthermore, it takes a language-based application development approach, so that only the necessary parts of the operating system are compiled with the application. To a certain extent, each TinyOS application is built into the operating system. TinyOS organizes components into layers. Intuitively, the lower a layer is, the "closer" it is to the hardware; the higher a layer is, the "closer" it is to the application. In addition to the layers, TinyOS has

unique component architecture and provides as a library a set of system software components. A component specification is independent of the component implementation. Although most components encapsulate software functionalities, some are just thin wrappers around hardware. The nesC language is used for programming. It is an extension of C to support and reflect the design of TinyOS v1.0 and above. It provides a set of language constructs and restrictions to implement TinyOS components and applications.

RIOT: It is a small operating system for networked, memory-constrained systems with a focus on low-power wireless Internet of Things (IoT) devices. It is based on microkernel architecture. RIOT allows application programming with C and C++ languages and provides multithreading and real-time abilities.

OpenTag: It is a DASH7 protocol stack & is designed to run on microcontrollers or a radio system on chip (SoC). It is written in C language. OpenTag is designed to be light and compact, as it is targeted to run on resource-constrained micro-controllers.

Nano-RK: "Nano" implies that the RTOS is small, consuming less power while "RK" is short for "resource kernel". It is an open source OS written in C and is a fixed, pre-emptive multitasking real-time operating system designed for use in WSN.

LiteOS: It is open source, written in C and Unix-like operating system that fits on memory constrained sensor nodes. LiteOS provides a familiar programming environment based on UNIX, threads and C. It follows a hybrid programming model allowing both event-driven and thread-driven programming.

MANTIS: The Multimodal system for Networks of In-situ wireless Sensors (MANTIS) provides a new multithreaded operating system for WSNs. It is an open source OS which is written in C. It provides automatic pre-emptive timeslicing for fast prototyping.

Contiki: It is an event-driven operating system. It makes the task of programming the sensor network closely resemble programming a PC. It is an open source OS. Contiki provides multitasking and a built-in Internet Protocol Suite (TCP/IP stack) with a full Graphical User Interface (GUI) features.

II. WSN SIMULATION SOFTWARE'S

Node-level design methodologies are usually associated with simulators that simulate the behaviour of a sensor network on a per-node basis. Using simulation, designers can quickly study the performance in terms of timing, power, bandwidth, and scalability of algorithms without implementing them on actual hardware and dealing with the actual physical phenomena. A node in a simulator acts as a software execution platform, as a sensor host, as well as a communication terminal. In order for designers to focus on the application level code, a node model typically provides or simulates a communication protocol stack, sensor behaviours e.g., sensing noise and operating system services. If the nodes are

mobile, then the positions and motion properties of the nodes need to be modelled. If energy characteristics are part of the design considerations, then the power consumption of the nodes needs to be modelled. Popular simulation software's are described below [6].

NS-2- The Network Simulator-2 (NS-2) is an open-source network simulator that was originally designed for wired, IP networks. Extensions have been made to simulate wireless/mobile networks (e.g., 802.11 MAC and TDMA MAC) and more recently sensor networks. While the original NS-2 only supports logical addresses for each node, the wireless/mobile extension of it introduces the notion of node locations and a simple wireless channel model. This is not a trivial extension, since once the nodes move, the simulator needs to check for each physical layer event whether the destination node is within the communication range. For a large network, this significantly slows down the simulation speed [7]. The main menu of NS-2 is shown in Fig. 2.

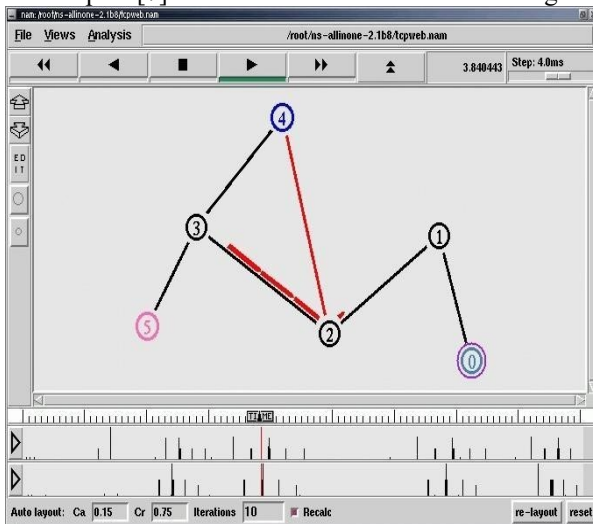


Fig. 2. The main menu of NS2 simulator software

The main functionality of NS-2 is implemented in C++, while the dynamics of the simulation (e.g., time-dependent application characteristics) is controlled by Tcl scripts. Basic components in NS-2 are the layers in the protocol stack. They implement the handlers interface, indicating that they handle events. Events are communication packets that are passed between consecutive layers within one node, or between the same layers across nodes. The main advantage of NS-2 is its rich libraries of protocols for nearly all network layers and for many routing mechanisms.

OMNET++-

It is a modular discrete events simulator implemented in C++. Getting started with it is quite simple, due to its clean design. OMNET++ also provides a powerful GUI library for 3-D virtualization, animation and tracing and debugging support. OMNET++ has been used in numerous domains from queuing network simulation to

wireless and ad-hoc network simulations, from business process simulation to peer-to-peer network, optical switch and storage area network simulations. OMNET++ opening menu is shown in Fig. 3 [8].

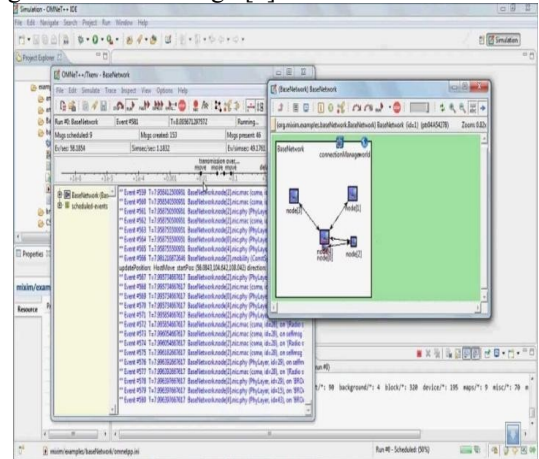


Fig. 3. The opening menu of OMNET++

J-Sim- A component-based simulation environment developed entirely in Java. The main benefit of J-sim is its considerable list of supported protocols, including a WSN simulation framework with a very detailed model of WSNs and an implementation of localization, routing and data diffusion WSN algorithms [9]. J-Sim main menu is shown in Fig. 4.

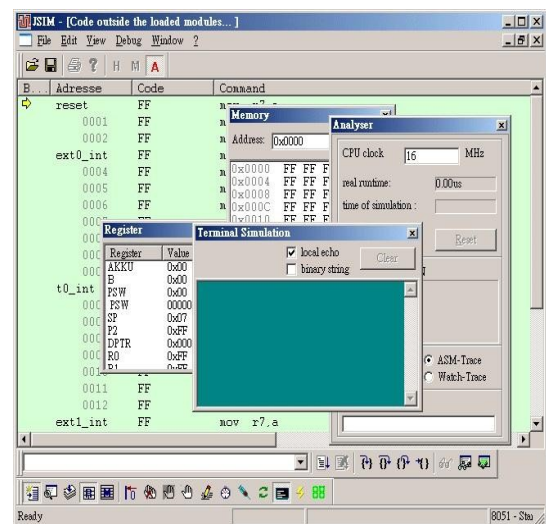


Fig. 4. J-Sim main menu with different windows

NCTUns2.0- It is a discrete event simulator whose engine is embedded in the kernel of a UNIX machine. The actual network layer packets are tunneled through virtual interfaces that simulate lower layers and physical devices [10] and its screen shot is shown in Fig. 5.

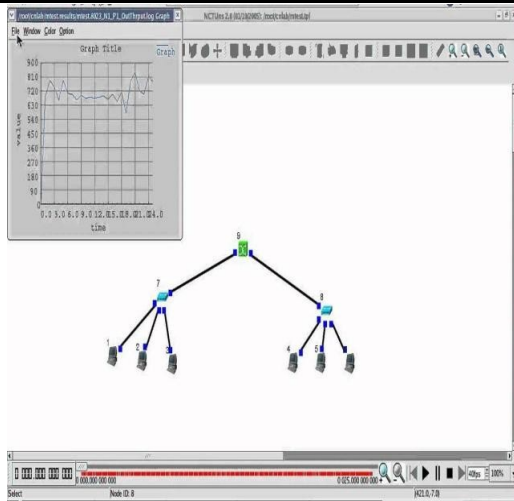


Fig.5.NCTUns2.0 simulator openingmenu

JiST/SWANS-JavaInSimulationTime(JiST)andScalable Wireless Ad-hoc Network Simulator (SWANS)are discrete event simulation framework that embeds thesimulationengineintheJava byte-code.Modelsareimplemented in Java and compiled. Then the byte-codesare rewritten to introduce simulation semantics. Javis is a packetflow and network animatorforJiST[11].Javissimulatoropeningmenuis showninFig.6.

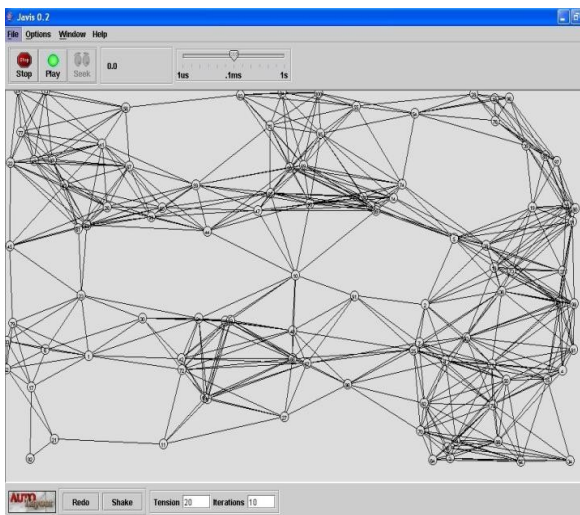


Fig.6.Javissimulatoropeningmenu

SSFNet- It is a set of Java network models built over theScalable Simulation Framework (SSF) for modeling andsimulation of Internet protocols and networks at and abovethe IP packet level. SSF is a specification of a commonAPIforsimulationthatassuresportabilitybetweencompli antsimulators.SSFNetmodelsare self-configuring i.e.eachSSFNetclassinstancecanautonomously configure itself by querying a configurationdatabase, which may be locally resident or available overthe Web [12]. SSFNet simulator execution screen shot isshowninFig.7.

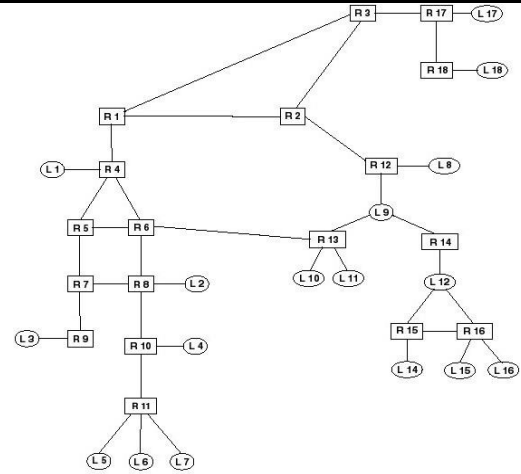


Fig.7.SSFetsimulatorExecutionscreenshot

GloMoSim-

SimulationenvironmentforwirelessnetworksbuiltwithParsec.Parsecis a simulationlanguage derived from C that adds semantics for creating simulation entities and message communication on a variety of parallel architectures[13].GloMoSimsscreenshotisshowninFig.8.

GloMoSim

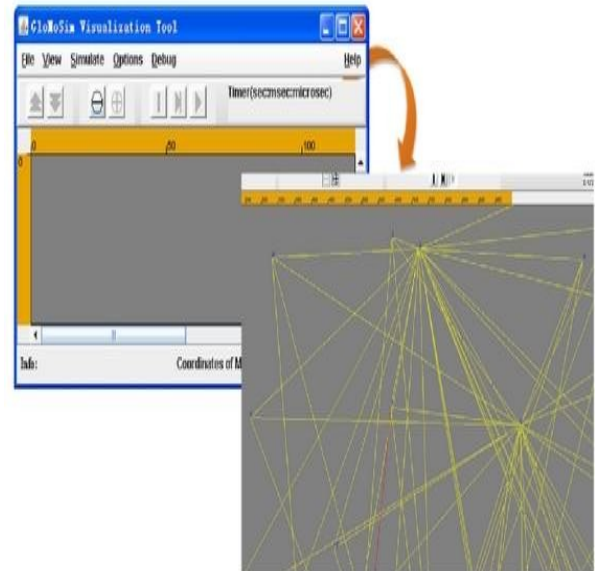


Fig.8.GloMoSimsimulator openingmenu

PtolemyII-ItcontainsJavapackages thatsupportdifferent models of simulation paradigms (e.g. continuoustime, dataflow, and discrete-event). It also addresses the modeling, simulation and design of concurrent, real-time, embedded systems. A major problem area being addressed is the use of heterogeneous mixtures of models of computation. The project is named after Claudius Ptolemaeus, the 2nd century Greek astronomer, mathematician, and geographer [14]. The opening menu of PtolemyII is shown in Fig.9.

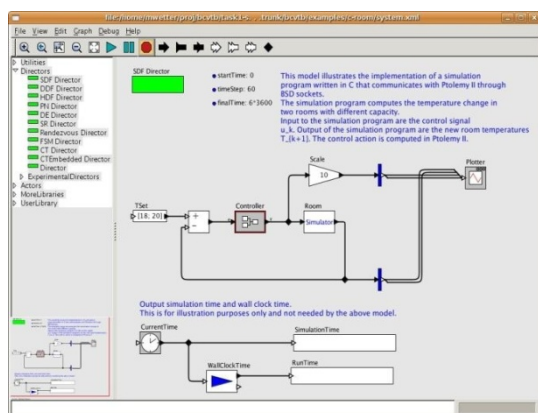


Fig.9.Openingmenu ofPtolemyII simulator

III. DIFFERENT WIRELESS TECHNOLOGIES

To Use wireless technology for different applications, the Institute of Electrical and Electronic Engineers (IEEE) has proposed standards and protocols according to its need. Table 1 lists the comparison of different standards [15].

Table 1. Comparison of different communication standards

Standard	Bluetooth	Infrared	Wi-Fi	ZigBee
Governing body	Bluetooth SIG	Infrared Data Association	Wifi Alliance	Zigbee Alliance
IEEE Specification	802.15.1	802.11	802.11 a/b/g	802.15.4
Frequency Band	2.4GHz	875nm+-	2.4GHz, 5 MHz	868/915MHz, 2.4 GHz
Standard range	1-100m	0.2-1m	100m	10-100m
Power Consumption (Days)	1 to 7	<200	1 to 5	100 to >1000
Number of RF channels	79	50	14	1/10, 16
Data transfer rate	3Mbits/s	4Mbits/s	4Mbits/s	50Kbits/s
Max. No. of nodes	8	2	2007	>65000
Modulation Type	GFSK	Pulse	BPSK, QPSK, M-QAM, CCM	BPSK(+ASK), O-QPSK
Applications	Cable replacement	Cable replacement	Web, Email, Video	Monitoring & control

IV. APPLICATIONS

WSN are used in various applications. The list of different areas and the possible parameters measurement are given below [16].

- Military or Border surveillance applications: Examples are Vehicle detection, Weapons, Chemical sensing etc.
- Environmental Applications: Examples are tracking the movements and patterns of insects, birds or small animals etc.
- Healthcare applications: Examples are Blood pressure, Heartbeat, Stress, Body temperature, Sleep, Brain activities etc.
- Home Intelligence: Examples are HVAC, Lighting control system, Security, Gas leak detection, Energy saving etc.
- Automobile Industry: Examples are Acceleration, Fuel consumption, Tire pressure, acknowledgment of illumination failures (turn lights, brake lights, front lights, and register plate lights) etc.
- Precision Agriculture: Examples are Water level, Temperature, Humidity, Soil Moisture, pH level, Wind flow, Light intensity etc.
- Structural Monitoring: Examples are Wind and Weather, Traffic, Deck, Pylons, Ground, Prestressing, Stray cables etc.
- Industrial Process Control: Examples are Temperature, Steam pressure, Liquid levels, Flow, Viscosity etc.
- Environmental Conditions Monitoring: Examples are Earthquakes, Volcano, Tsunami, Fire, Flood, Pollution etc.
- Oil and Gas industry: Examples are Oil bunkering and theft, pipeline vandalization etc.

V. CONCLUSION

Wireless networking advancements, as well as the integration of MEMS-based sensors and actuators with embedded microprocessors, have enabled a new generation of massive-scale sensor networks suited for a variety of commercial and military applications. Sensor networks have the potential to connect end users directly to sensor measurements and deliver information that is precisely localized in time and/or location to meet the needs of the users. There are various different types of OS for WSNs, each with its own set of features, benefits, and drawbacks. Because of the limitation of resources, WSN operating systems are typically less complex. TinyOS was the first operating system designed specifically for WSNs. TinyOS differs from other operating systems in that it uses event-driven programming, whereas others use multithreading.

Simulators that replicate the behaviour of a sensor network on a per-node basis are known as node-level design simulators. Designers can quickly assess performance in terms of timing, power, bandwidth, and scalability using simulation rather than implementing them on real hardware and dealing with physical phenomena. The overview includes suggestions for choosing a suitable simulation model for a WSN as well as a detailed discussion of the most commonly used tools. All of the packages include a graphical user interface.



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interface. The OMNET++, NCTUns2.0, J-Sim, and Ptolemy II GUI libraries provide advanced animation, tracing, and debugging capabilities. Simulators that run in parallel should perform and scale better than those that run sequentially. When considering the new environment and the energy components, modelling issues occur. They also jeopardise scalability and precision. For a better understanding and characterization of sensor networks and their accompanying simulators, a thorough examination of these challenges is required. The ZigBee standard, developed by the ZigBee Alliance, is used to create WSNs that require high reliability, low cost, and low power for monitoring and control applications.

Military, environmental applications, healthcare, home intelligence, automobile industry, precision agriculture, structure monitoring, industrial process control, environmental condition monitoring, oil and gas industry, and others are among the different application fields of WSN.

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